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# **Multiparty Finite Computations**

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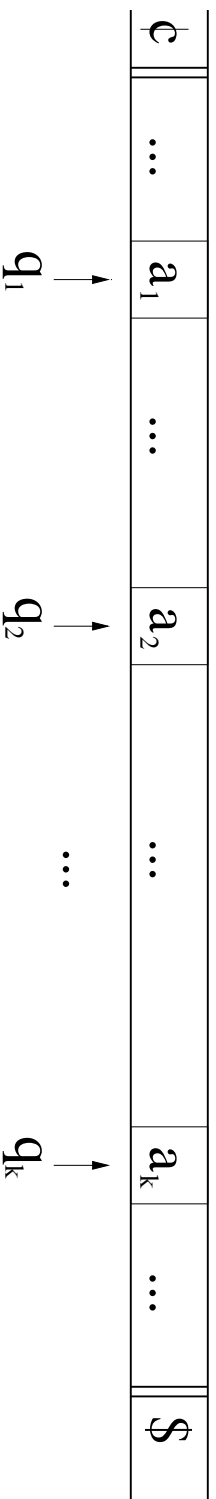
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**some results in cooperation**

**with P. Ďuriš (Comenius University, Bratislava)**

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## ***Multihed Finite Automata: cooperation***



- each automaton may send a message after each step
- transition function of a single automaton depends on the input symbol currently seen and messages sent by the other automata

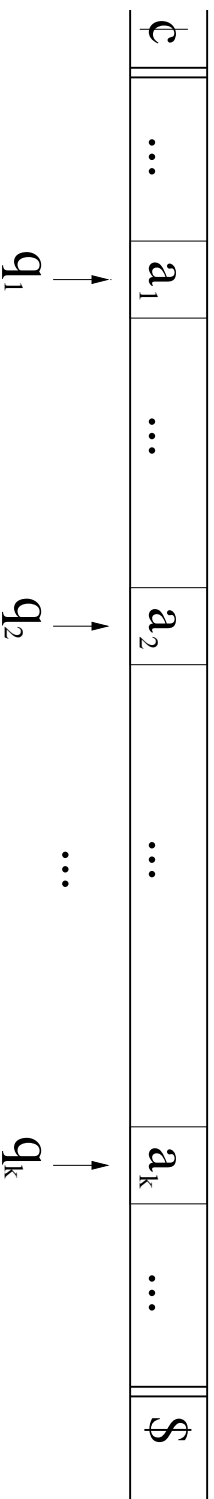
$$(q'_i, r) = \delta(q_i, a, m_1, \dots, m_{i-1}, m_{i+1}, \dots, m_k)$$

where  $m_j$  is the message sent by the  $j$ th automaton after previous step.

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## ***Multiprocessor Finite Automata: common master***



- Each processor is a **genuine** finite automaton, it does not receive any messages
- **The master**: after each step inspects the states of all processors and determines which processors are **frozen** and **active**:

$$h(i, q_1, \dots, q_k) \in \{\text{ACTIVE, FROZEN}\}$$

where  $i$  is the processor number and  $q_1, \dots, q_k$  – the states of all processors

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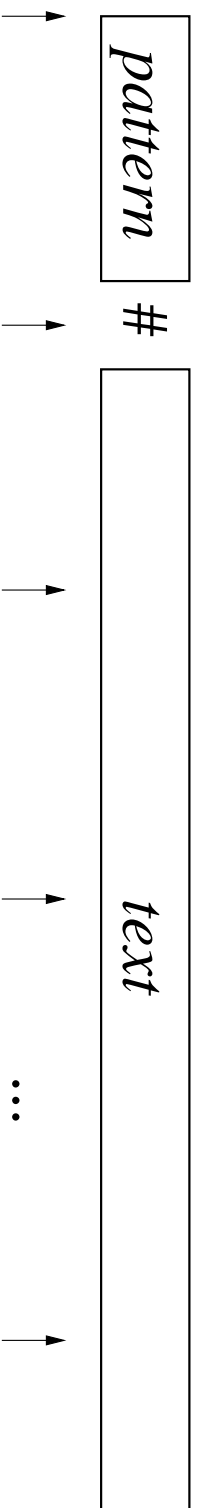
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## Classical problems

**Sensing sensing vs *non-sensing* heads** (Duris, Galil – 1995)

**Pattern matching** by one-way, deterministic *sensing* automata (Jiang,

Li – 1993)



**Hardware** the number of automata vs computational power

(Yao, Rivest – 1976; Monien – 1980)

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## New problems

**Means of cooperation :**

Cooperation means vs computational power.

Computational power of *multiprocessor* vs *multithread* systems

**Communication :**

Communication volume vs computational power

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## Message complexity classes

$MESSAGE_l(k(n))$

– the languages that may be recognized by systems of  $l$  automata where at most  $k(n)$  messages are sent for every input word of length  $n$

$MESSAGE(k) = \bigcup_l MESSAGE_l(k)$

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## Motivations

1. “Communication” Complexity
  - Does the weaker mode of communication between devices decrease their computational power?
  - How the limitation of communication size influence the power of devices?
  - Communication complexity of problems in the case, when other resources are bounded.
2. Computation on sequential devices vs computation on devices with random access to memory (example: complexity of matrix transposition)

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## Obvious properties

1.  $k$  heads are at least as powerful as  $k$  processors (coordinated by a master)
2.  $\{a^n b^n : n \in \mathbb{N}\}$  can be recognized with 2 one-way processors, by 2 one-way heads with a single message, (not a regular language!)
3.  $\{a^n b^n c^n : n \in \mathbb{N}\}$  can be recognized by 2 one-way heads (not a context free language!)
4.  $\bigcup_{k=1}^{\infty} \text{2-YH}(k) = \text{YLOGSPACE}$  for  $Y \in \{\mathbf{N}, \mathbf{D}\}$



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## Results: Heads vs Processors

### 1. Simulations

- $X\text{-NH}(k) = X\text{-NP}(k)$  for every  $k \in \mathbb{N}$  and  $X \in \{1, 2\}$
- $X\text{-DH}(k) \subseteq X\text{-DP}(k+2)$  for every  $k \in \mathbb{N}$  and  $X \in \{1, 2\}$

### 2. Separation

- $1\text{-DP}(2) \not\subseteq 1\text{-DH}(2)$

### 3. Closure properties

- $\bigcup_{k=1}^{\infty} 2\text{-NP}(k)$  and  $\bigcup_{k=1}^{\infty} 2\text{-DP}(k)$  are closed under complement
- $\bigcup_{k=1}^{\infty} 1\text{-NP}(k)$  is not closed under complement
- $1\text{-DP}(k)$  is closed under complement for every  $k > 2$

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## Results: Size of Communication

1. The hierarchy for the communication of constant size:
    - (a)  $MESSAGE(k-1) \not\subseteq MESSAGE(k)$  for one-to-one model
    - (b)  $MESSAGE(k-1) \not\subseteq MESSAGE(k+l-1)$  for on-bus model
  2. probably a gap between  $MESSAGE(O(1))$  and  $MESSAGE(\Theta(\log n))$ .
  3. The languages which have the complexity of communication between  $\log n$  and  $n$  form quite a dense hierarchy.
  4. There are languages in  $MESSAGE(\Theta(n))$ .
  5. Matrix multiplication requires  $n^{3/2} / \log^{2+\epsilon} n$  messages. (easy proof, also follows from two-party communication of branching programs)
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## Separation between heads and processors

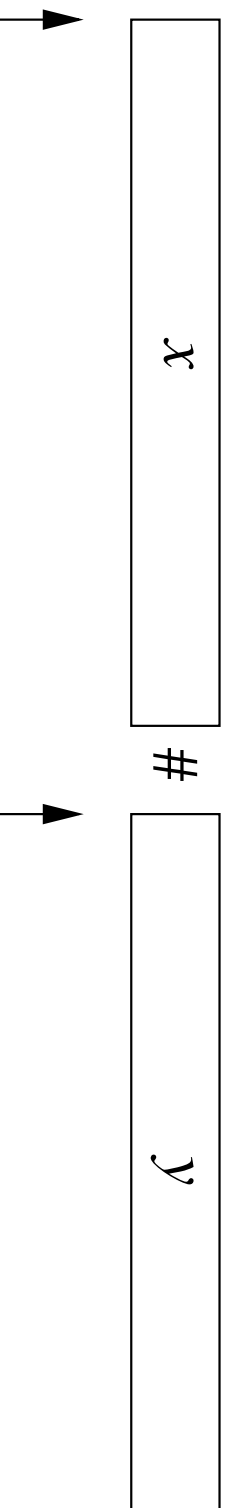
**Theorem** For  $|\Sigma| \geq 3$  the language

$$L_P = \{x\#y : x, y \in \Sigma^*, |x| = |y|, p(x, y) = 1\}$$

separates classes **1-DP**(2) and **1-DH**(2), where  $p(x, y)$  is the parity of the number of positions on which  $x$  and  $y$  differ.

*How to recognize  $L_P$  by two-head one-way deterministic automaton:*

- heads scan  $x$  and  $y$  simultaneously and synchronously
- one of the heads changes its states between **ODD** and **EVEN** on every position in which  $x$  and  $y$  differ



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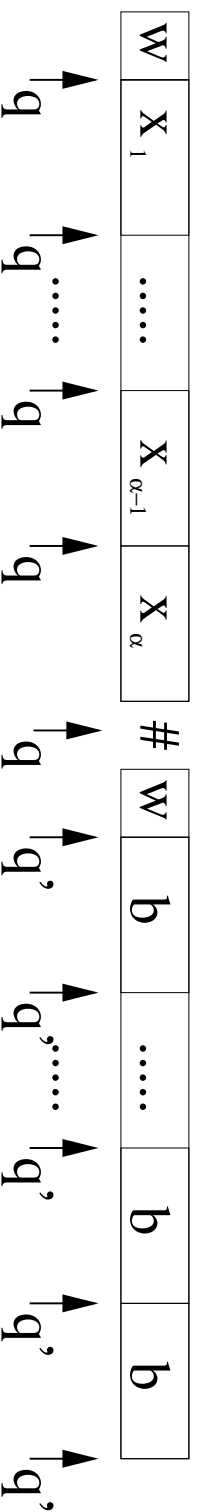
## Separation: a sketch

Why two processors cannot recognize  $L_P$  (intuition):

1. Processors have to compare  $x$  and  $y$  simultaneously.
  2. The only possibility to recognize current parity of the number of differences is to “desynchronize” processors on  $x$  and  $y$
  3. For appropriately constructed input words it is necessary to increase or decrease (monotonically) difference between positions of processors on  $x$  and  $y$
  4. The difference between positions of processors comparing appropriately constructed words  $x$  and  $y$  will grow too much contradicting 1.
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## Separation: details

The set of words  $W$  on which we cheat the automaton:



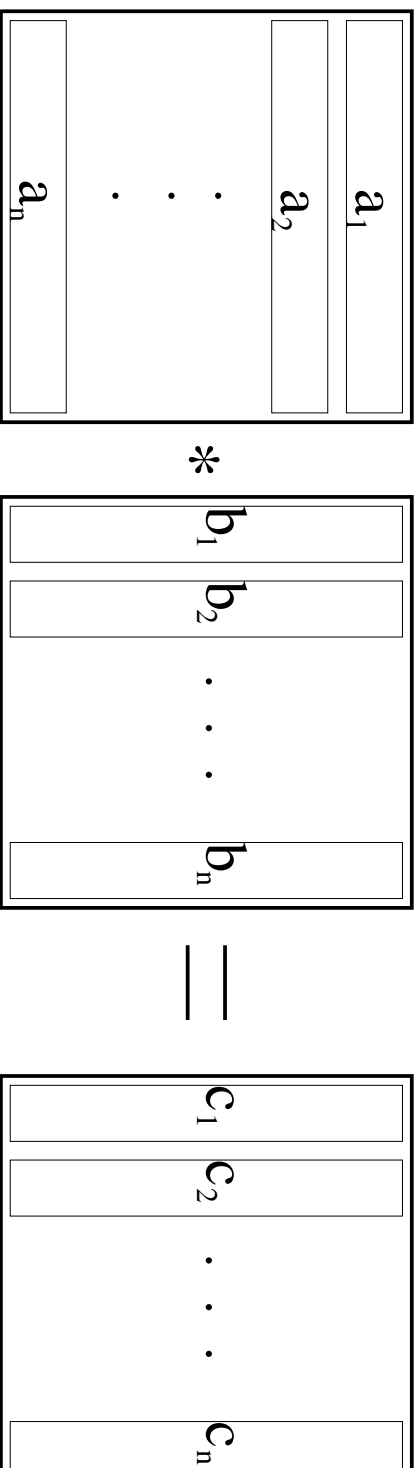
- $x_i = a_1$  OR  $x_i = a_2$  for every  $i$
- $|a_1| = |a_2| = |b| = n$
- $p(a_1, b) \neq p(a_2, b) = 0$
- $K(a_i|b) \geq n - c \log n, \quad K(b|a_i) \geq n - c \log n$
- both processors start and finish computation on every  $x_i$  and on  $b$  in the same state

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## **Systems of finite automata which compute functions**

1. The read-only tape includes the arguments of the function
2. The result of the function is written on one-way write-only tape with one head
3. Example: The representation of matrix multiplication problem: arguments are stored as a sequence of rows (the first matrix) and a sequence of columns (the second matrix)

# Matrix multiplication problem



$a_1$   $\dots$   $a_n$   $b_1$   $\dots$   $b_n$  input data

$c_1$   $\dots$   $c_n$  output

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## The lower bound for the matrix multiplication

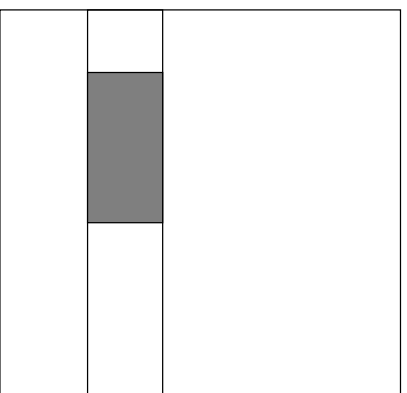
**Theorem 1** *The matrix multiplication function requires  $\Omega(N^{3/2} / \log^{2+\varepsilon} N)$  messages for every  $\varepsilon > 0$ . ( $O(N^{3/2})$  suffice by the straightforward algorithm.)*

### Sketch of the proof

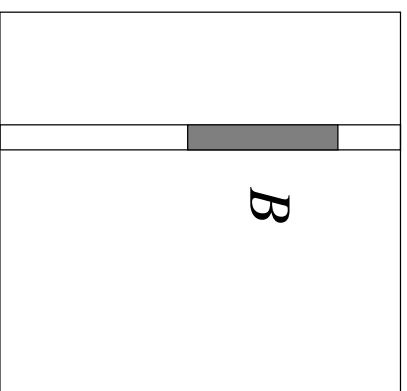
1. We consider matrices with large Kolmogorov complexity
2. We divide the computation on the stages. One stage consists of the part of computation in which  $s(n)$  bits of the result are written
3. The amount of communication in one stage is “almost”  $(n/s(n))$  when  $s(n) = \omega(\log n)$



# Matrix multiplication - one stage

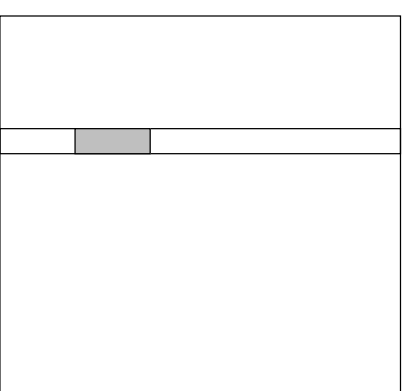


$X$



$B$

=



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## Matrix multiplication - one stage

1. During the stage we multiply the submatrix  $A$  by the vector  $B$
2. Let  $B'$  be the longest subword of  $B$  on which no message was sent
3. Let  $A'$  be the submatrix of  $A$  corresponding to the block  $b'$
4.  $A'$  has a big non-singular submatrix  $A_N$ ,  
the product with an appropriate subvector  $b'$  of  $b$  is uniquely determined without knowledge of  $b'$
5. we encode  $b'$  as one of the vectors giving this result while multiplied with  $A_N$

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## Conclusions and open problems

**Conclusion:** multiprocessor automata have **similar** computational power to multithread automata, but in some cases heads are **more powerful** than processors

**Conclusion:** The amount of communication substantially influence the power of systems of finite automata.

**Problem:**  $1\text{-DP}(k) \stackrel{?}{\not\subseteq} 1\text{-DH}(k)$  for  $k > 2$ ,  $2\text{-DP}(k) \stackrel{?}{\not\subseteq} 2\text{-DH}(k)$  for  $k > 1$

**Problem:** Are there any languages which require a non-constant, sub-logarithmic number of messages?

**Problem:** a superlinear lower bound on the communication size for a decision problem.

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